

Random Dynamical Systems and Stochastic Structural Stability

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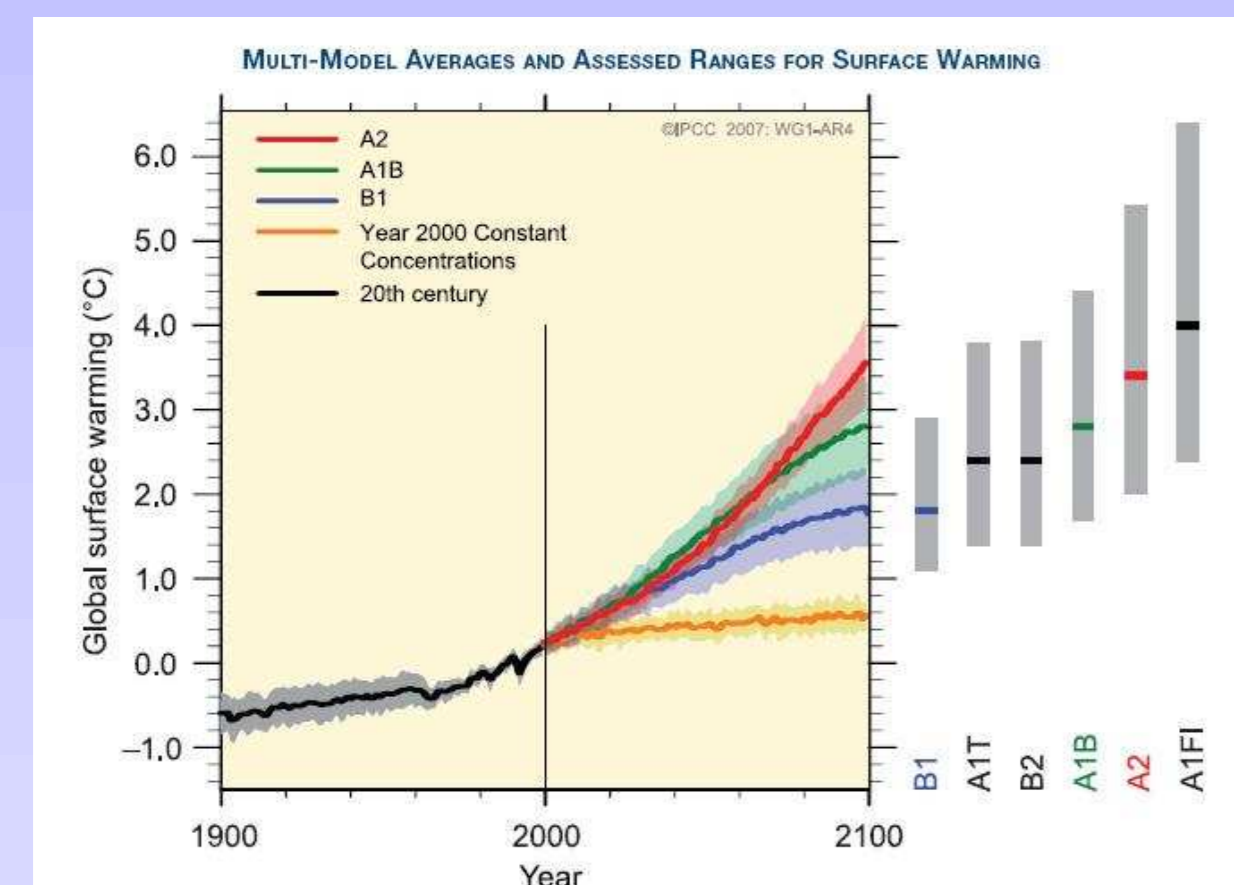
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1. Can we reduce uncertainties in climate projections?

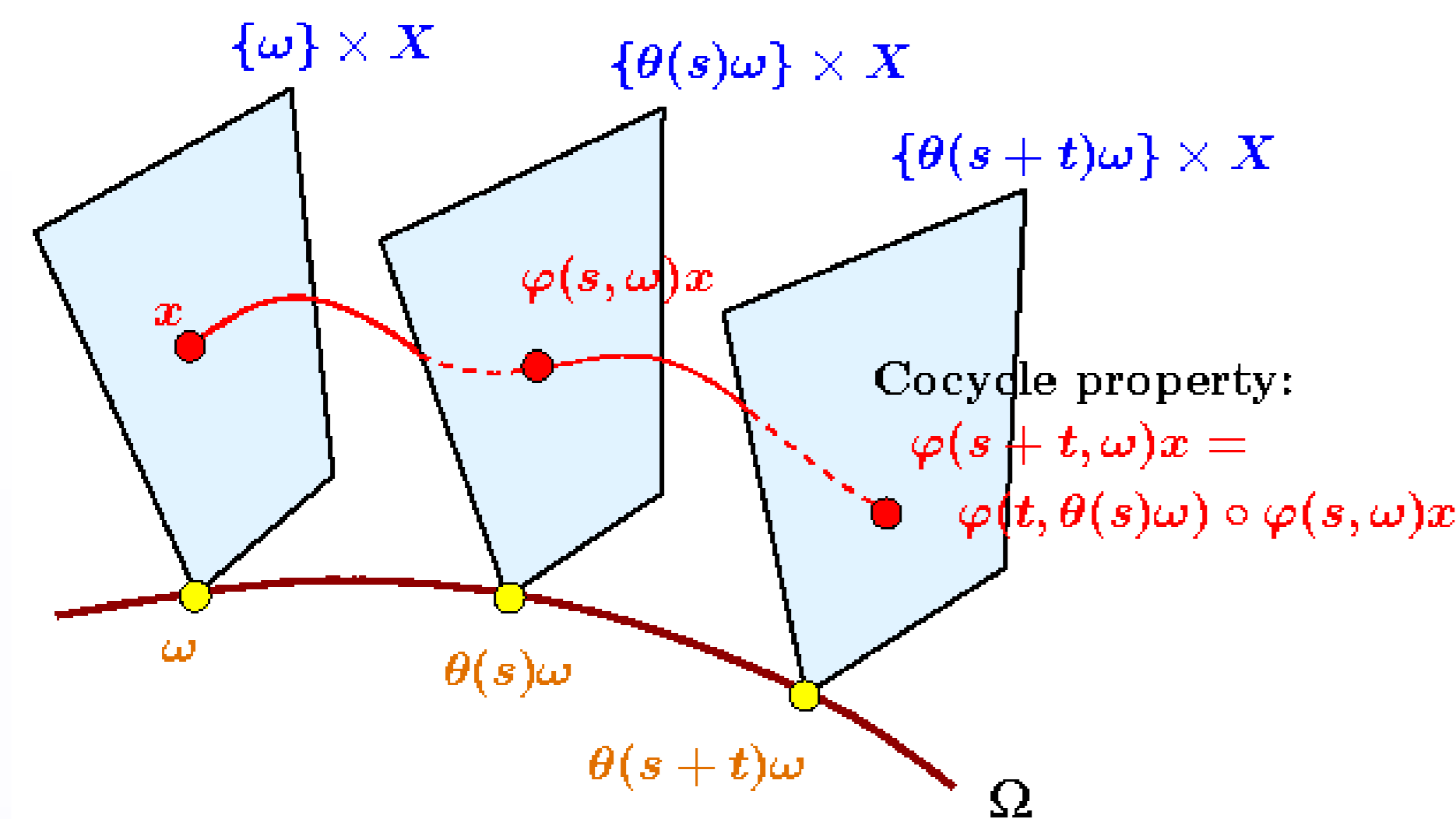
- Last IPCC report (AR4): GCM overfitting over 20th century leads to divergent behavior for the latter part of the 21st century.



- This problem may be due to the fact that GCMs are structurally unstable, in the sense of deterministic dynamical systems.
- In fact, the climate system contains unresolved, random components \Rightarrow need for stochastic parametrizations in GCMs and hence a new concept of structural stability \Rightarrow Random Dynamical Systems.

2. What are Random Dynamical Systems (RDS)?

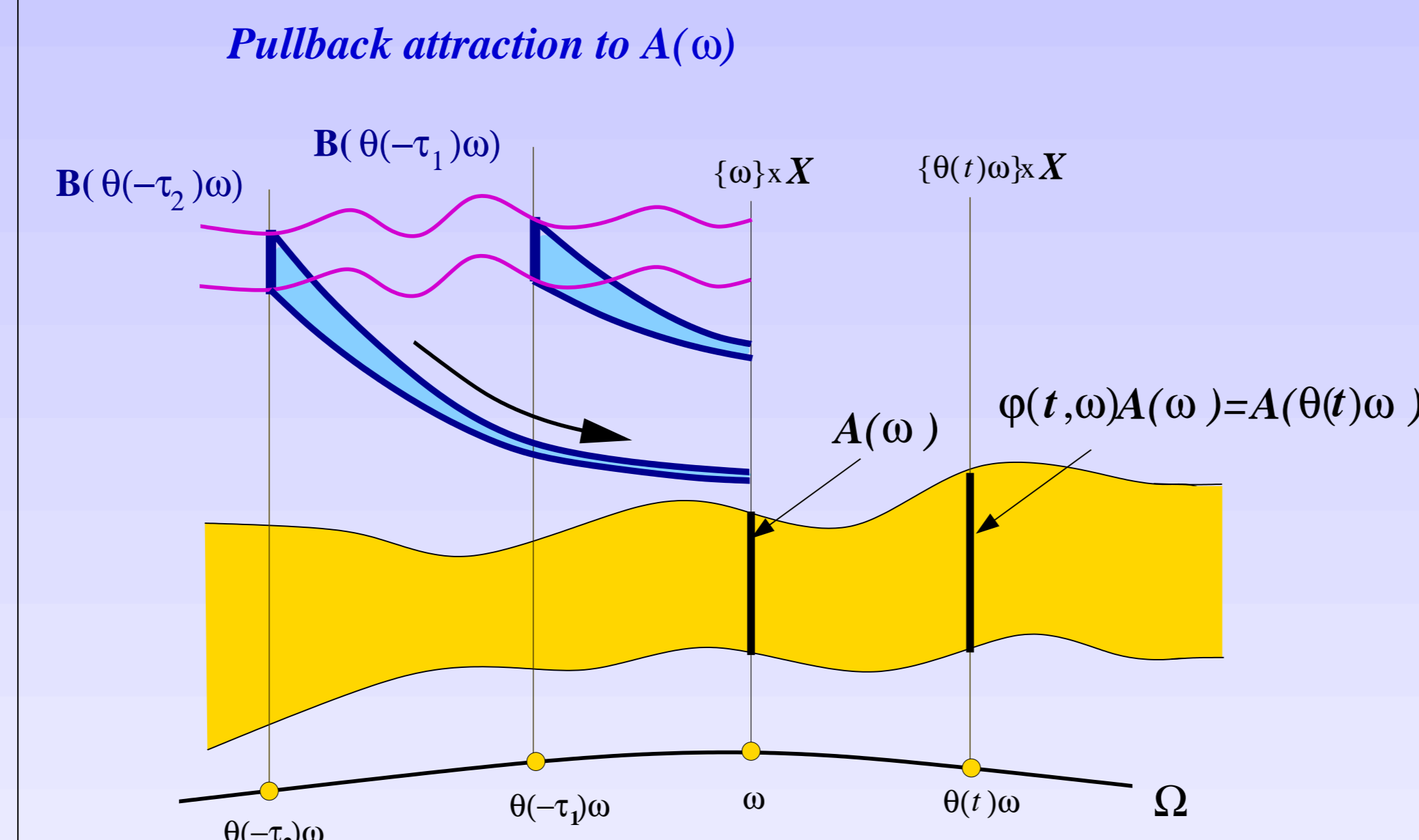
- RDS theory is a combination of measure and dynamical systems theory: “Bremen group” — L. Arnold (1998).
- RDS provide a geometric description of random systems: Flows on the bundle “Probability space” \times “Phase space” X .



- φ is a random dynamical system
- $\Theta(t)(x, \omega) = (\theta(t)\omega, \varphi(t, \omega)x)$ is a flow on the bundle
- $\theta(t)$ is a model of the noise; it is called the driving system and must preserve the statistics!

3. What we would like to do first

- We want to compare the dynamical behavior of several GCMs in a “smart way.”
- Comparing merely the probability density functions (PDFs) is not sufficient to understand the differences in underlying dynamics.
- We use the concept of **random attractor** $\mathcal{A}(\omega)$ and **stochastic topological conjugacy**:



- Stochastic conjugacy**: two cocycles $\varphi_1(t, \omega)$ and $\varphi_2(t, \omega)$ are conjugated iff there exists a **random homeomorphism** h (i.e., a random, but smooth change of variables) such that:

$$\varphi_1(t, \omega) = h(\theta(t)\omega)^{-1} \circ \varphi_2(t, \omega) \circ h(\omega)$$

- We want to classify GCM behavior using these RDS tools and to study this classification as a function of the noise intensity. To do so, we consider “toy” models first.

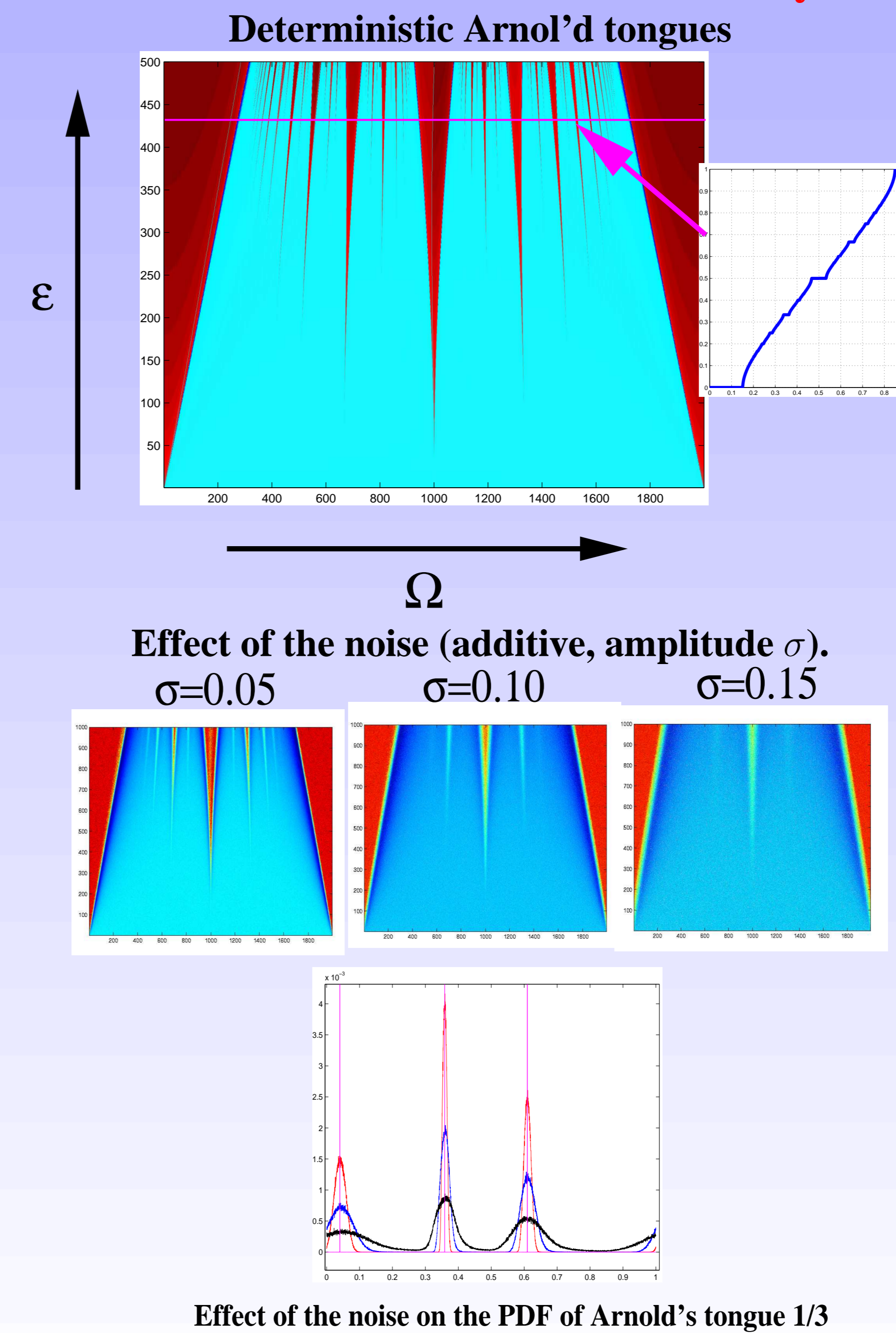
4. VI. Arnol’d’s family of diffeomorphisms of the circle

- We want to perform a classification in terms of **stochastic equivalence**.

$$x_{n+1} = F_{\Omega, \epsilon}(x_n) := x_n + \Omega - \epsilon \sin(2\pi x_n) \text{ mod } 1$$

- Frequency-locking phenomena and the Devil’s staircase
- Topological classification of the Arnol’d family, in parameter space:
 - countable regions of structural stability vs.
 - uncountable structurally unstable systems with nonzero Lebesgue measure.
- Two types of attractors: periodic orbits vs. the whole circle S^1 (see next section).

5. Effect of the noise on the Arnol’d family



- The number of classes becomes **FINITE**: only the most robust tongues survive!
- Irrational rotations becomes all stochastically equivalent to $\mathcal{A}(\omega) = \{a(\omega)\}$, where a is a random point.
- The noise has a dramatic impact on the sensitivity to the initial state.

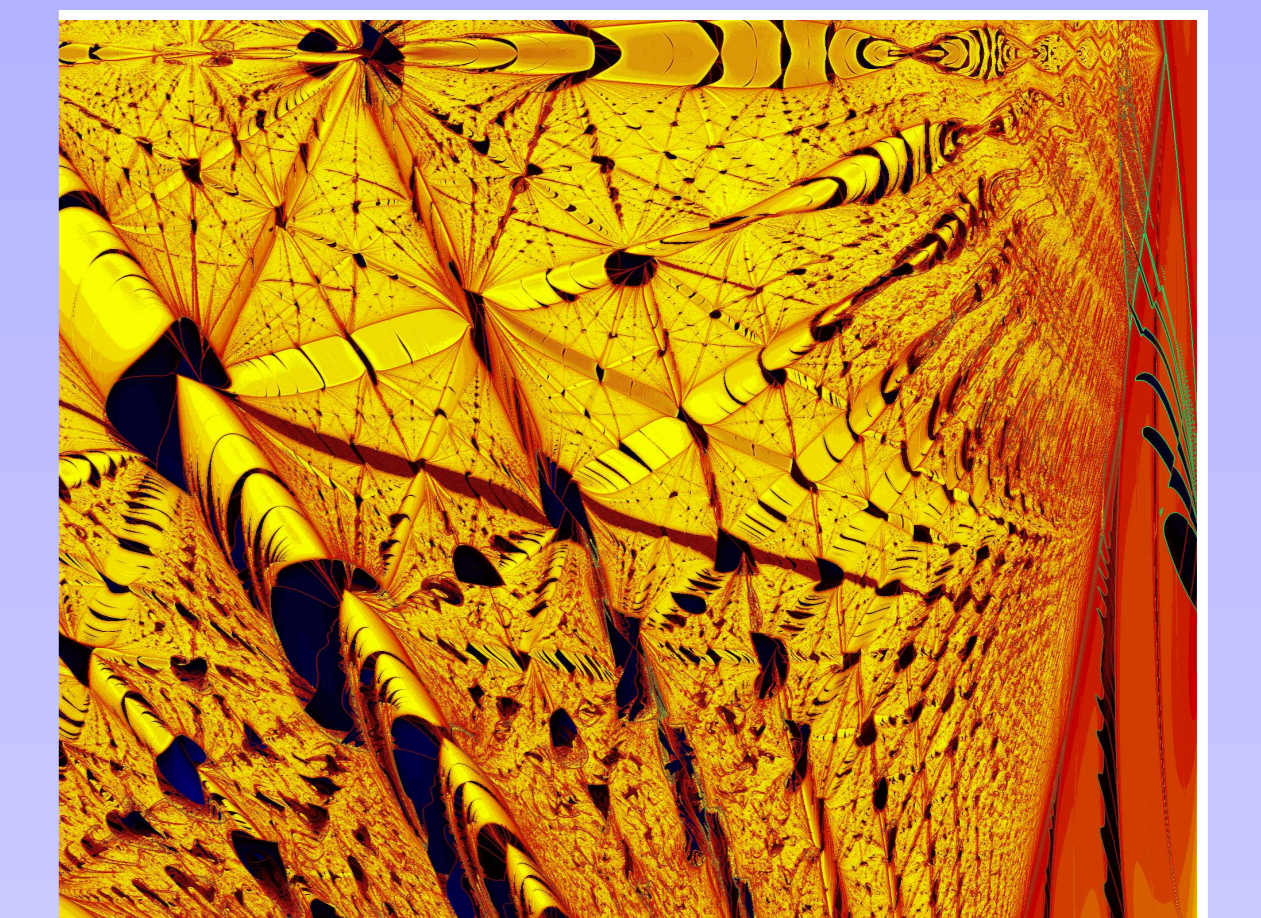
6. The torus map: a paradigm of complex systems

We extend the previous toy model to a more complex one:

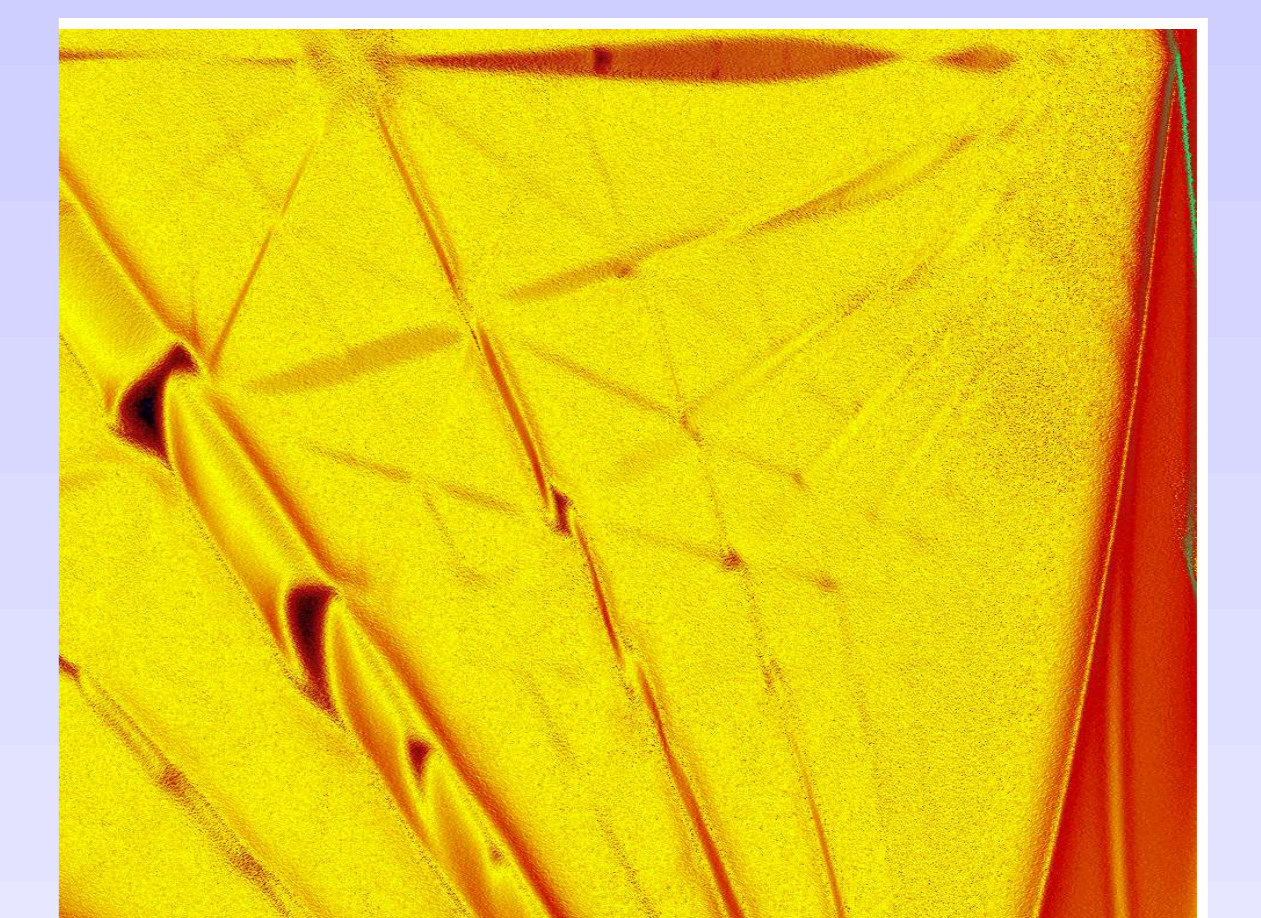
$$\begin{aligned} x_{n+1} &= x_n + \Omega_1 - \epsilon \sin(2\pi y_n) \text{ mod } 1 \\ y_{n+1} &= y_n + \Omega_2 - \epsilon \sin(2\pi x_n) \text{ mod } 1 \end{aligned}$$

- Web of resonances** (partial and full) + **chaos** !
- This provides a more realistic paradigm of observed dynamics.

Deterministic web of resonances



Effect of the noise (additive, amplitude $\sigma = 0.15$).



- The web of resonances is nonlinearly modified. This smoothing is linked with stochastic normal form theory.

7. Concluding remarks

- Collapse** of the attractor’s dimension: $\lim_{\sigma \rightarrow 0} \dim \mathcal{A}_\sigma(\omega) < \dim \mathcal{A}_0$ as the noise intensity σ goes to zero — is this always the case?
- Stochastic parametrization \Rightarrow **gain of structural stability** for random attractors.
- These results hold for pertinent deterministic models that are stochastically perturbed.
- RDS theory offers a meaningful framework for classifying rich behavior in stochastic modeling.

References

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