

Modelling of Ensemble Covariances

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Background

- Canadian NWP centre currently has both a global 4D-Var (for deterministic forecasts) and EnKF (for probabilistic forecasts)
- Provides good opportunity to compare two approaches and to evaluate use of flow-dependent ensemble background-error covariances in a variational system
- Current approaches for modelling background-error covariances in 4D-Var and EnKF represent two extreme cases:
 - 4D-Var: horizontally homogeneous, nearly temporally static
 - EnKF: independently estimated at each grid-point and analysis time
- Unlikely that either approach is optimal, best approach probably somewhere in between
- Therefore, both systems could be improved with a more general approach to covariance modelling (focus is on correlations in following)

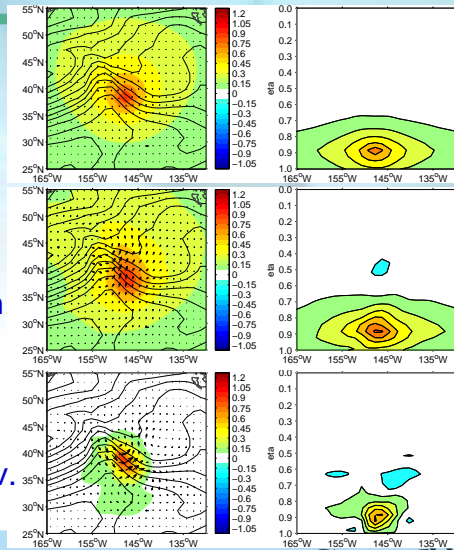
Comparison of Covariances used in 3/4D-Var and EnKF

- Corrections to T and UV in response to a single T obs near the surface
- Black contours show background T
- EnKF error covariances from 128 ensemble members

3D-Var

4D-Var
(obs at end of 6h window)

EnKF
error cov.



Outline

- Demonstrate complementary effects of spatial and spectral localization applied to ensemble-based error correlations
- Implementation issues in realistic NWP variational assimilation systems
- Simpler approach to incorporate limited amount of heterogeneity

Sampling error in ensemble-based error covariances

- Test ability of ensemble-based covariances to reproduce “true” covariances as function of ensemble size and spatial localization
- Spatial localization:

$$\mathbf{B}_{\text{grid_loc}} = \mathbf{B}_{\text{samp}} \circ \mathbf{L}_{\text{grid}}$$

where \mathbf{L} is a simple “correlation” matrix with monotonically decreasing values as a function of separation distance used to do the localization

- Use operational \mathbf{B} matrix as “truth” (homog/isotr. correlations for main analysis variables), generate ensemble members:

$$\mathbf{e}^k = \mathbf{B}^{1/2} \boldsymbol{\varepsilon}^k \quad \text{where } \boldsymbol{\varepsilon}^k = \mathcal{N}(0, \mathbf{I})$$

- Final value of J_o (all operational data) used as simple measure of accuracy of ensemble-based covariances: ability to fit to observations

Effect of ensemble size and spatial localization on sampling error

Final value of J_o (normalized by value from using “true” \mathbf{B}) as a function of ensemble size and localization radii:

| Localization radii | | Ensemble size | | | |
|--------------------|------------------|---------------|------|------|----------|
| Horizontal (km) | Vertical (ln(P)) | 32 | 128 | 512 | ∞ |
| ∞ | ∞ | 3.15 | 3.10 | 2.98 | 1.00 |
| 10 000 | ∞ | 2.72 | 2.30 | 1.77 | 0.96 |
| 2 800 | ∞ | 2.09 | 1.46 | 1.12 | 0.84 |
| 10 000 | 2 | 2.23 | 1.73 | 1.31 | 0.94 |
| 2 800 | 2 | 1.47 | 1.11 | 0.97 | 0.82 |

Spectral correlation localization

- What happens if same type of localization is applied to the correlation matrix in spectral space?
 - A diagonal correlation matrix in spectral space corresponds with globally homogeneous correlations
 - Represents an extreme case of spectral correlation localization
 - More moderate spectral localization should result in correlations with an intermediate amount of heterogeneity
- Was shown that **localization of correlations in spectral space** (multiplication) is equivalent with **spatial averaging of correlations in grid-point space** (convolution)
- Averaging of correlations over a **local** region should be better than either globally homogeneous or independent for each grid point:
 - reduced sampling error through averaging, but
 - still maintain most of spatial/flow dependence of correlations

Spectral correlation localization

- **Localization of correlations in spectral space** (multiplication):

$$\mathbf{S} \mathbf{B}_{\text{spec_loc}} \mathbf{S}^T = (\mathbf{S} \mathbf{B}_{\text{samp}} \mathbf{S}^T) \circ \mathbf{L}_{\text{spec}}$$

where

\mathbf{S} is spectral transform,

\mathbf{L}_{spec} is a "correlation" matrix with monotonically decreasing values as a function of the absolute difference in wavenumber

- **Spatial averaging of correlations in grid-point space** (convolution):

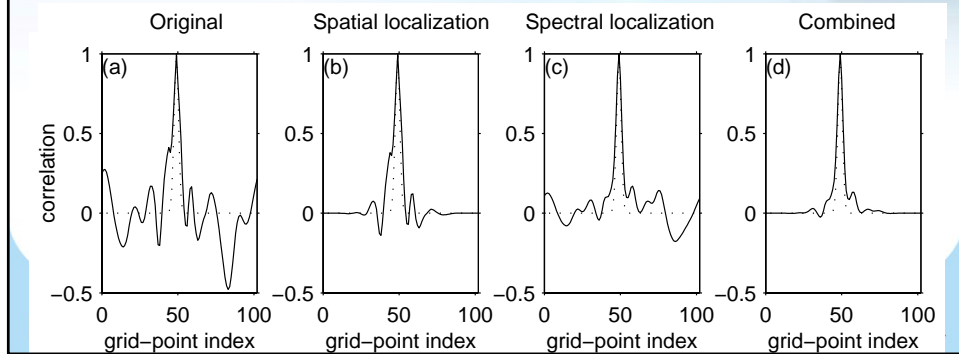
$$\mathbf{B}_{\text{spec_loc}}(x_1, x_2) = \int \mathbf{B}_{\text{samp}}(x_1+s, x_2+s) \mathcal{L}_{\text{spec}}(s) ds$$

where

$\mathcal{L}_{\text{spec}} = (\mathbf{S}^{-1} \mathbf{L}_{\text{spec}} \mathbf{S}^T)$ assuming \mathbf{L}_{spec} is homogeneous and isotropic in wavenumber space

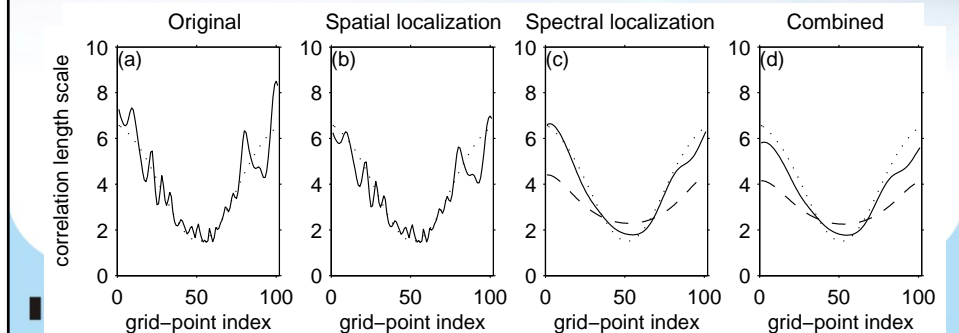
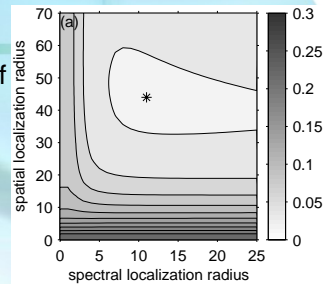
Spatial and spectral correlation localization

- Idealized 1-D example using prescribed “true” heterogeneous correlations and estimated correlations from 30 realizations
- Spatial localization cannot improve short-range correlations
- Spectral localization cannot remove long-range spurious correlations
- Combination seems to give best result



Spatial and spectral correlation localization

- For this example, a unique optimal combination of spatial and spectral localization exists (minimum rms error of correlations)
- Spectral localization dramatically improves local estimate of correlation length scale: $(-d^2C/dx^2)^{-1/2}$
- With too much spectral localization, start to lose heterogeneity (dashed)



Ensemble-based error covariances in 3D-Var

- Implementation in preconditioned variational analysis:
 - no localization: elements of control vector determine **global** contribution of each ensemble member to the analysis increment:

$$\Delta x = \sum (e^k - \langle e \rangle) \xi^k \quad (\xi^k \text{ is a scalar})$$

- spatial localization: elements of control vector determine **local** contribution of each ensemble member to the analysis increment:

$$\Delta x = \sum (e^k - \langle e \rangle) \circ (L_{\text{grid}}^{1/2} \xi^k) \quad (\xi^k \text{ is a vector})$$

- in each case, J_b is Euclidean inner product:

$$J_b = 1/2 \xi^T \xi$$

- can also combine with standard **B** matrix:

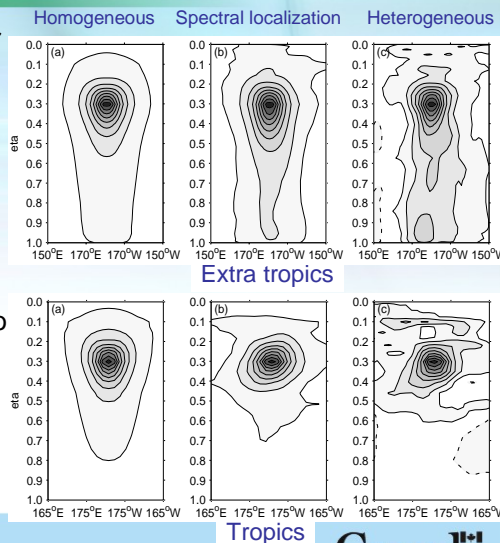
$$\Delta x = \beta^{1/2} \sum (e^k - \langle e \rangle) \circ (L_{\text{grid}}^{1/2} \xi^k) + (1-\beta)^{1/2} B^{1/2} \xi_{\text{HI}}$$

Spectral correlation localization

- Apply in variational system, similar technique as spatial localization
- Elements of control vector determine local contribution (in spectral space) to analysis increment:

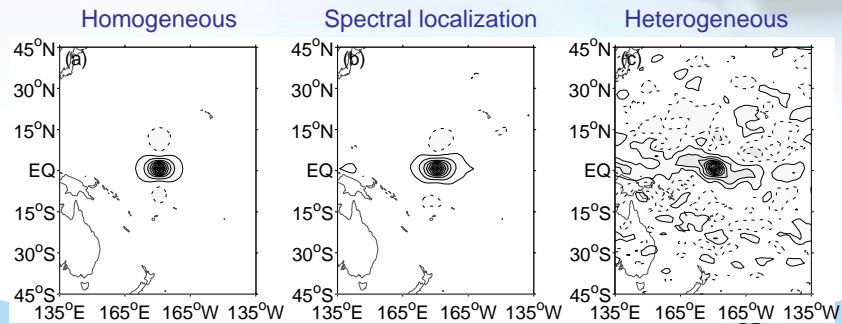
$$\Delta x = S^{-1} \sum (S(e^k - \langle e \rangle)) \circ (L_{\text{spec}}^{1/2} \xi^k)$$

- Spectral correlations forced to zero beyond total wavenumber difference of 10 (Gaussian-like function)



Spectral correlation localization

- Still need to apply spatial localization to damp long-range spurious correlations, however
- Current approach may become **prohibitively expensive** (memory or time) when combining spatial and spectral localization



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Combining spatial and spectral correlation localization

- transform ensemble members into functions of **space and scale**:

$$e^k(x) = \sum_n e^k(n) \exp(i2\pi nx) = \sum_n e^k(x, n) \quad (\text{but too big to store})$$

- both control vector (ξ) and L depend on **space and scale**, but L could be separable:

$$L_{\text{spec,grid}}(x_1, x_2, n_1, n_2) = L_{\text{grid}}(x_1, x_2) L_{\text{spec}}(n_1, n_2)$$

- follow same approach as before:

$$\Delta x = \sum_k \sum_n (e^k(x, n) - \langle e(x, n) \rangle) \circ (L_{\text{spec,grid}}^{1/2} \xi^k(x, n))$$

- J_b is still the same form: $J_b = 1/2 \xi^T \xi$
- some similarities with wavelet approach are evident



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Simpler approach for resolving limited amount of spatial heterogeneity

- Tested a simple approach for resolving Tropical vs. Extra-Tropical differences in error correlations in NWP variational system
- Use current approach for modelling homogeneous correlations, but estimate separate statistics for three latitude bands

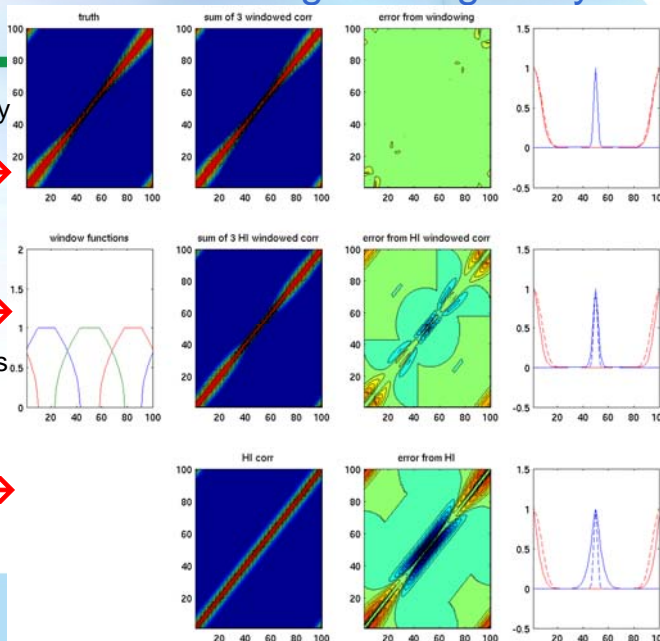
- Construct increment by combining 3 separate increments:

$$\Delta x = \alpha_{nh}(\text{lat}) B_{nh}^{1/2} \xi_{nh} + \alpha_{tr}(\text{lat}) B_{tr}^{1/2} \xi_{tr} + \alpha_{sh}(\text{lat}) B_{sh}^{1/2} \xi_{sh}$$

- Weighting functions (α) constructed to conserve total variance within transition zones
- Also results in some limited spatial localization

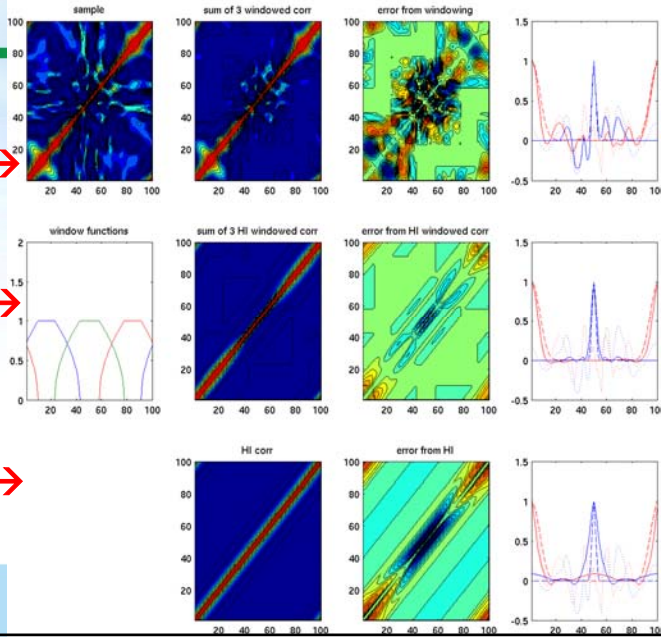
Simpler approach for resolving heterogeneity

- Simple 1D experiment, smoothly varying length scale
- Divide correlations into 3 regions and apply to "truth" →
- Compare with making corr in each region homogeneous. →
- Also compare with making correlations homogeneous over entire domain →



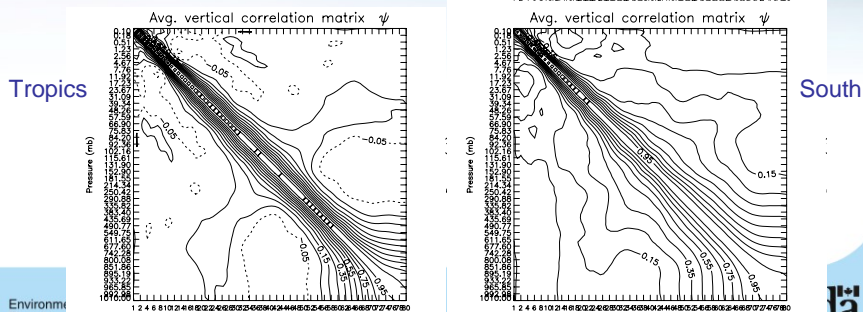
Simpler approach for resolving heterogeneity

- Apply to sample estimate of correlations (N=20)
- Divide correlations into 3 regions and apply to sample estimate
- Compare with corr homogeneous in each region
- Also compare with making correlations homogeneous over entire domain



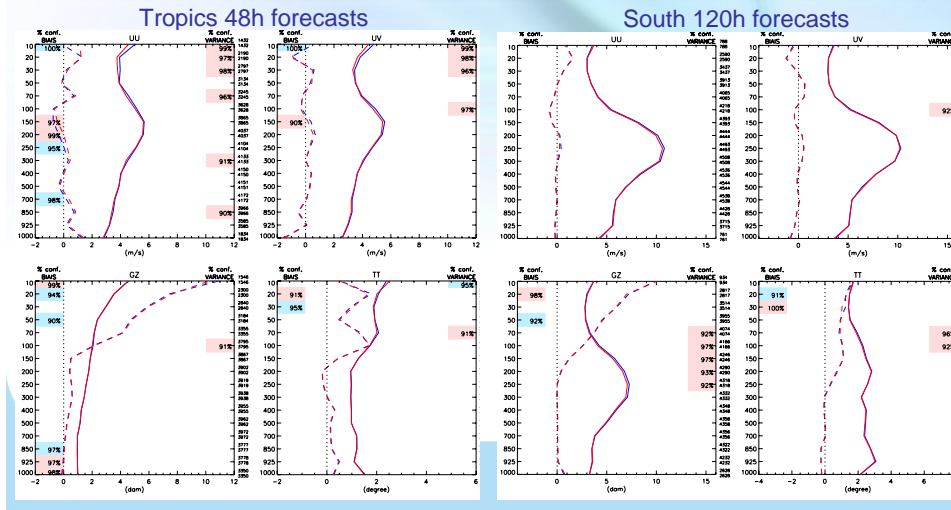
Simpler approach for resolving heterogeneity

- Tested approach with new NWP system under development
- Vertical correlations of streamfunction shown for 3 latitudinal bands (NMC method)
- Relatively easy to implement, but control vector 3 times larger



Simpler approach for resolving heterogeneity

- Verifications against radiosondes of forecasts from 2 month 3D-Var experiments with **3 zonal bands** vs. **globally homogeneous correlations**



Extra Slides

Plan for testing EnKF covariances in 4D-Var

- Prompted by workshop planned for November 2008 in Argentina
- Currently, EnKF and 4D-Var are too different to allow useful comparison: horizontal resolution, deterministic vs. probabilistic, etc.
- Design experiments to isolate specific differences:
 - 1) **standard EnKF**: use ensemble mean for verification (low-res)
 - 2) **“deterministic” EnKF**: additional member with no perturbations to simulate obs or model error (low-res)
 - 3) **incremental “deterministic” EnKF**: additional deterministic member at higher horizontal resolution than EnKF ensemble
 - 4) **incremental 4D-Var with ensemble-based B**: ensemble-based error covariances at beginning of assimilation window with same localization as EnKF
 - 5) **incremental 4D-Var with static B**: same as operational deterministic analysis system

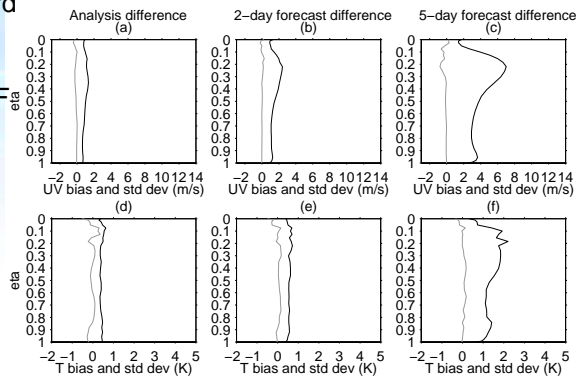
Plan for testing EnKF covariances in 4D-Var

Specific differences whose impact could be evaluated:

- **smoothing of ensemble mean relative to deterministic forecast:**
 - 1) standard EnKF vs. 2) “deterministic” EnKF at same resolution
- **different analysis approach with equal covariances at beginning of assimilation window:**
 - 3) incremental “deterministic” EnKF vs. 4) incremental 4D-Var with ensemble-based B
- ***impact of flow-dependent ensemble-based covariances in 4D-Var:**
 - 4) ensemble-based error covariances vs. 5) static covariances

Earlier tests with EnKF error covariances

- Impact of EnKF vs. standard 3D-Var error covariances
- Horizontal and vertical localization applied to EnKF covariances
- Single case of rapidly developing system over Pacific (12 UTC, 27 May 2002)
- Bias (grey curves) and std dev (black curves) of the analysis and forecast differences



Earlier tests with EnKF error covariances

- Forecast error measured vs. analyses from CNTL assimilation experiment
- General improvement from using EnKF error covariances
- Small improvement also seen in scores averaged over 2 week forecast-analysis experiments
- Should revisit, now 4D-Var and EnKF has also been improved

